

Stereo Vision Camera Configuration

- 2 sets of cameras
- 1 set located on the top - Wider panoramic view
- 1 set located on the front side
 - Responsible for determining clear obstacles



1 set located on the top side

1 set located on the front side

Lawrence
@Tech













University of Cincinnati

Lawrence Tech

Handwritten notes on a whiteboard, including the heading "Robot" and several lines of text.



UW
ROBOTICS TEAM
UNIVERSITY OF
Waterloo
GM
Navitel
eCE

University of Waterloo
WatBot







CATERPILLAR
SUPPORTING DESIGN

RoboJackets
NATIONAL INSTRUMENTS
www.robogjackets.org

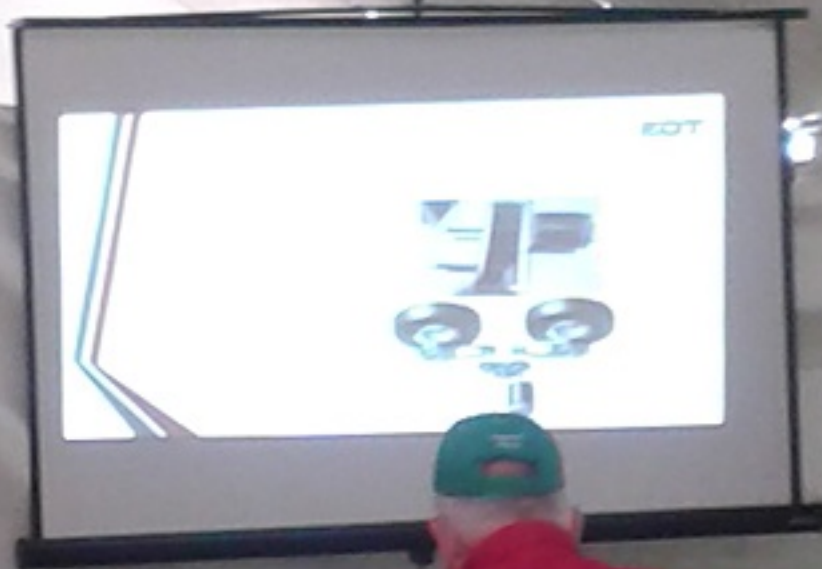
Sponsors: CATERPILLAR, Intel, National Instruments, NATIONAL INSTRUMENTS, RoboGT, and others.

The C-Team
SPIKE

Intel
MIRIUS

IT - Bharat
Pushpak





МАОНА
МАШИНОСТРОЕНИЕ



